

Using Cameras for Measurements

2021 Training #2

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Purpose

- In fulfillment of requirement, "Training in observations planning, detector settings, and imaging performance"
 - See "UCB Letter on additional tasks_09.28.21.pdf"
- Viewing this material should prepare you for planning observations using the BSTI camera.

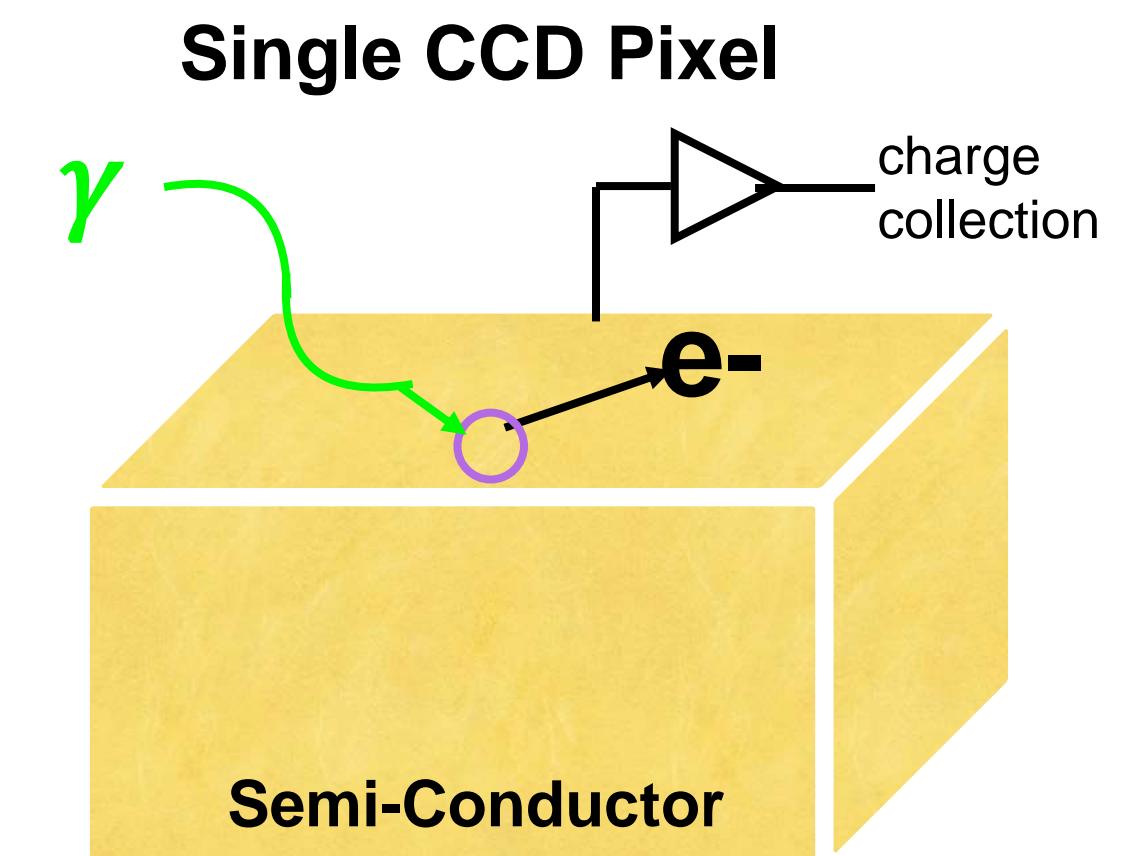
Sensors for Astronomy

- Charge-Coupled Device, or CCD.
 - CCDs can detect 1- a few HUNDRED THOUSAND photons



CCD Sensor

- **Physics:** a single photon interacts in semi-conductor to “free” an electron for collection
 - said to “pop” electron into conduction (energy) bands where they can move and be collected
 - Each pixels is a detector; electrons are pushed across the detector’s rows and columns for counting.



- **Electronic Noise:** tiny bit from “reading” CCD
 - Noise $\sim 5 e^-$, for constant targets, collect until lots of e^-
 - But short exposures => few e^- from target, $5e^-$ noise
 - **short exposures NO GOOD - too many noise e^- !**

Noise in Measurements

- Noise adds in “quadrature” = $(\sigma^2_{\text{read}} + \sigma^2_{\text{Poisson}} + \sigma^2_{\text{other}} + \dots)^{1/2}$
 - where σ^2_{read} is the electronic noise from reading CCD.
 - $\sigma_{\text{Poisson}} \rightarrow N e^{-1/2}$ for N large (otherwise you integrate Poisson distribution).
- Longer exposures always more sensitive:
Signal $\sim t_{\text{exp}}$; Noise $\sim \text{sqrt}(t_{\text{exp}})$ so
$$\text{S/N} \sim t_{\text{exp}}^{1/2}$$
- Noise = $(\sigma^2_{\text{read}} + \sigma^2_{\text{Poiss}} + \dots)^{1/2}$ so expose until $\sigma^2_{\text{Poiss}} \gg \sigma^2_{\text{read}}$.
 - » This gives minimum t_{exp} and limits time resolution.

Basic Basics of Astronomical Imaging

- Measurement aperture has some number of pixels $N_{\text{pix,ap}}$.
total readout noise = $\sqrt{N_{\text{pix,ap}}}$ * single pix read out noise
- Signal in aperture has noise: Poisson($N_{\text{e-}}$, signal)
-> $\sqrt{N_{\text{e-}}$, signal) is $N_{\text{e-}}$ large ($\sim > 50$)
- To set Texposure: **NOT readout-dominated regime**
 - don't saturate anything of interest!
 - make $\sqrt{N_{\text{e-}}$, signal) > a few * total readout noise
==> Noise dominated by nature, not electronic artifact
 - if target signal small compared to background, calculate signal as background, "background-dominated" regime. Take many such frames ==> max dynamic range for standard stars, etc.

Basic Basics 2

- How do I go from ADU to e-?

K-gain! Conv. mode 100kHz hfreq -> K-gain = 3.473 e-/ADU.

CAUTION: This is only CHANGE in ADUs with time....

- BIAS and ZERO POINT

Texp~ 0s frames have ~ 1490 ADU in typical Conv. exposures.

-----> Subtracting bias takes care of most of this.

-----> IMPORTANT: LOOK at over-scan region, last line of CCD covered by metal, no light:
See only offset+ dark current.

- ADU to e-

- 15 s images:~ 1503 ADU in bgnd pix

- bgnd signal= 1503 ADU - (over-scan=1491) = 12 ADU / pix

- 12 ADU * (k-gain = 3.473 e-/ADU) = 41.4 e-; in 15 s==> bgnd rate = 2.76 e-/s

What is brightness of sky, typical source?

- Faint source ~ 17.75 mag $\rightarrow 9e-/s$ peak pix; bgnd $\sim 2.8 e-/s$

- How did I get this?

- 201015a, 15 s images: ~ 1503 ADU bgnd/pix
BUT overscan line ~ 1491 ADU zero-point offset,
MUCH BIGGER THAN SIGNAL!
- 1503 ADU bgnd pix -1491 ADU = 12 ADU bgnd signal;
in 15 s, that's $12/15=0.8$ ADU/s bgnd
vfreq $8e5$ hfreq $3.33e6$ \Rightarrow k-gain $3.538e-/adu$.
Finally, 0.8 ADU/s $\times 3.538 e-/ADU = 2.83 e-/s$
- **Faint source** ~ 17.75 mag; **peak** is 1529 ADU or
 38 ADU/ 15 s $\Rightarrow (3.538 e-/ADU \times 38 ADU)/15s$
 $\sim 9e-/s$ peak pix.

characteristic	r'
zero-point (ADU/pix)	1491 (1)
bgnd/pix e-/s	2.83 (1)
FWHM (pix)	3.5 (1)
bgnd/1 FWHM circ aperture (e-/s)	27.2 e-/s (1)

Basic Basics 3

- **ALWAYS bias-subtract!!!!**

- Large offsets just confuse you. As we say on last slide, offset often \gg signals

- **Convert frames to e-/s using K-gain**

Will help you understand Poisson noise

bepsimr0009.fits=(imr0009.fits - median_bias.fits)/kgain;

b for bias subtracted, **eps** for units of e- per secon.

- **Someday soon: flat corrections!**

- **f**epsimr0009.fits=(imr0009.fits - median_bias.fits)/kgain/medflatr.fits

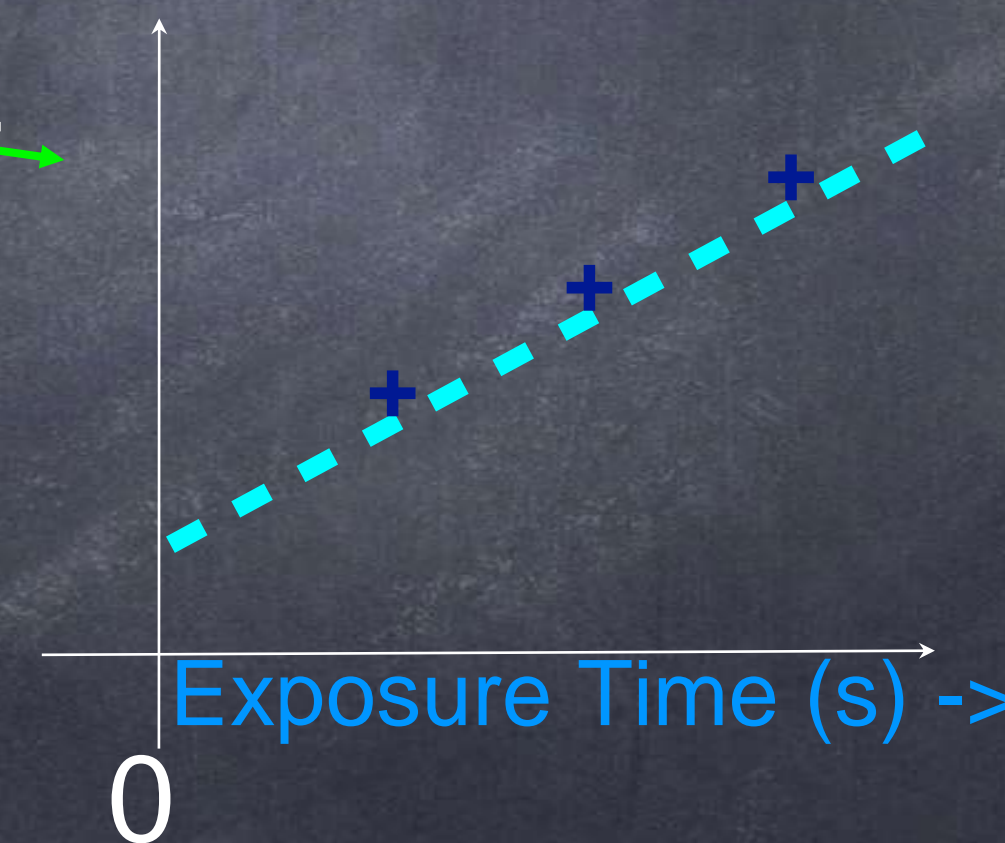
f for flat-corrected.

Technology For Transient Imaging:

- *Need sensitivity **and** time resolution **and** dynamic range*
 - Fast transients means need time resolution
 - Fainter transients still need sensitivity
 - **Random alerts** means we cannot know which are super-bright, good for high time resolution studies, which are faint, need longer exposures.
- These are the conditions for NUTTeIA transients from Swift:
We can never know the brightness before hand, so we need to understand what our EMCCD settings mean in all potential cases.

Imaging Measurements

- Standard CCDs- pix detectors that convert photons \rightarrow electrons (e^-) \rightarrow ADU
- Add up numbers in **aperture**, subtract background, gives flux, desired measurement.
- The longer you expose an image, the more ADU (e^- s) you get.
- A CCD is only read at the end of the exposure \Rightarrow sampling time = exposure time, which gives **time resolution of measurements**.
- Since pixels are numbers, can add images sky-pixel to sky-pixel, called "**co-adding**", for more **signal and sensitivity**.



What is high-time resolution for?

Can't cross-correlate with just a few points!

Need time resolution

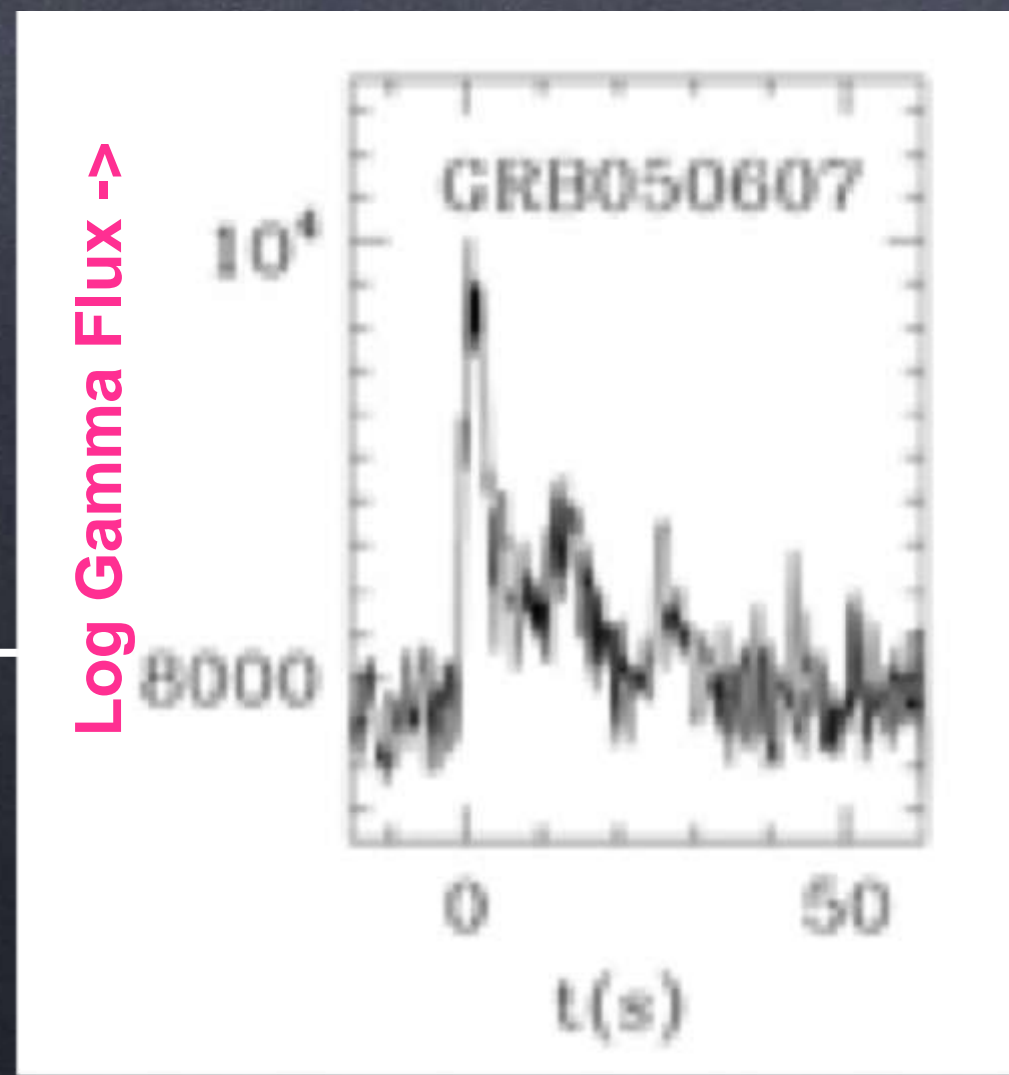
Important if spectrum changes during burst

Timescale of each pulse important in some theories

Reverse shock emission component does not have fast variability

Cross-correlation of gamma and optical signal measures what fraction of optical from same process as gamma.

Log Optical Flux ->



Log Time ->

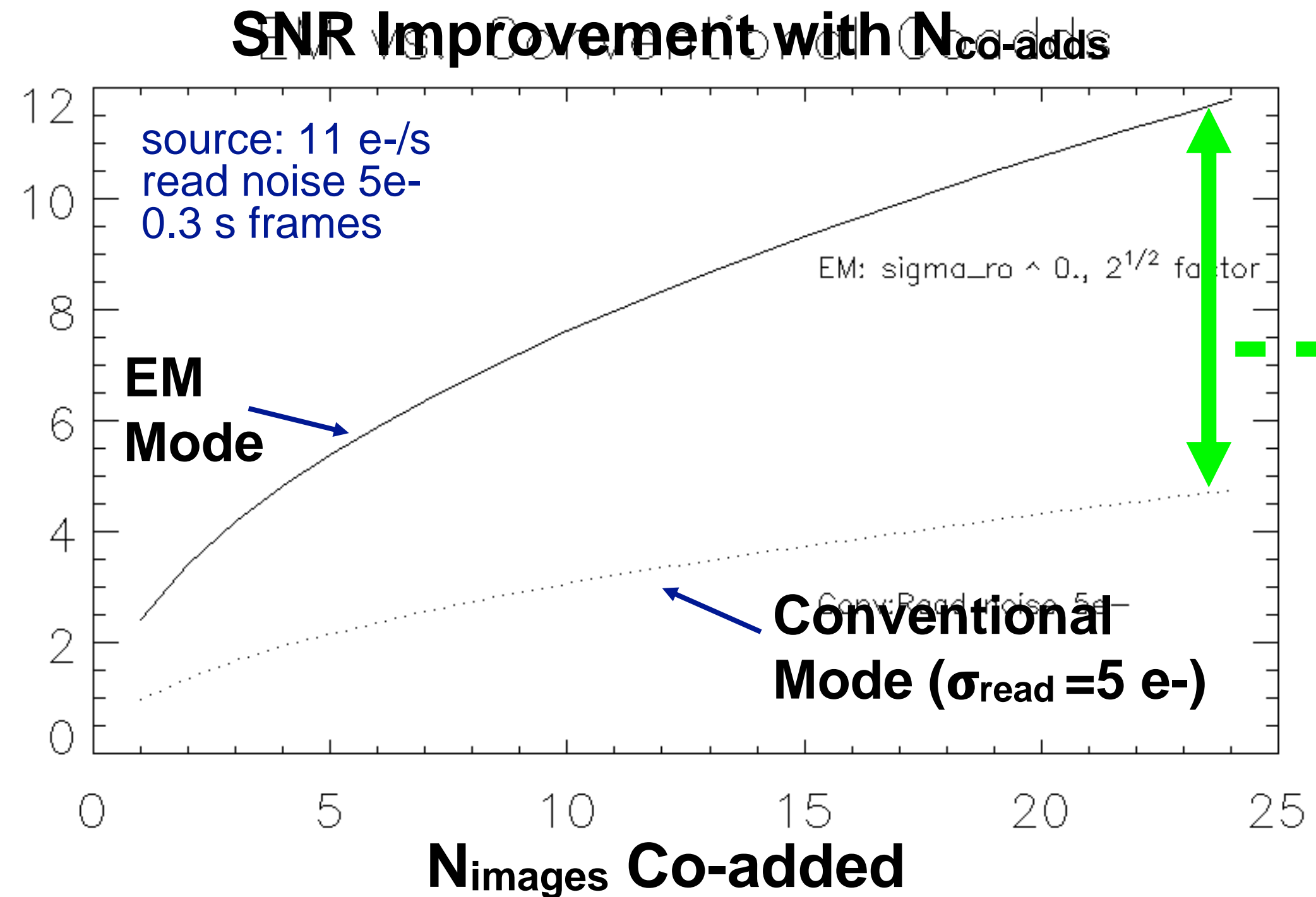
Co-adding: time resolution or noise?

- Take short, e.g. 0.1 s frames:
 - » good time resolution!, but faint sources not detected
 - » Fix: if faint, co-add frames for enough signal to detect
 - right?
 - How does this affect noise?
- Noise = $(\sigma^2_{\text{read}} + \sigma^2_{\text{Poiss}} + \dots)^{1/2}$ so for co-add:
Noise(Nframes) = $(N_{\text{frames}} \times \sigma^2_{\text{read}} + N_{\text{frames}} \times \sigma^2_{\text{Poiss}} + \dots)^{1/2}$
 - » Co-adds just keep adding σ^2_{read} , huge noise!
 - » Co-add conundrum:
 - Short exposures— good time resolution, but **add read noise**
 - Single long exposure —lower noise, but **NO time resolution!**
- **Beat this with EMCCD!**

EM co-adds allow choice: time resolution v. SNR

- SNR co-adding short frames of faint source.
- EM mode SNR grows faster vs Conventional mode

Signal / Noise (SNR)

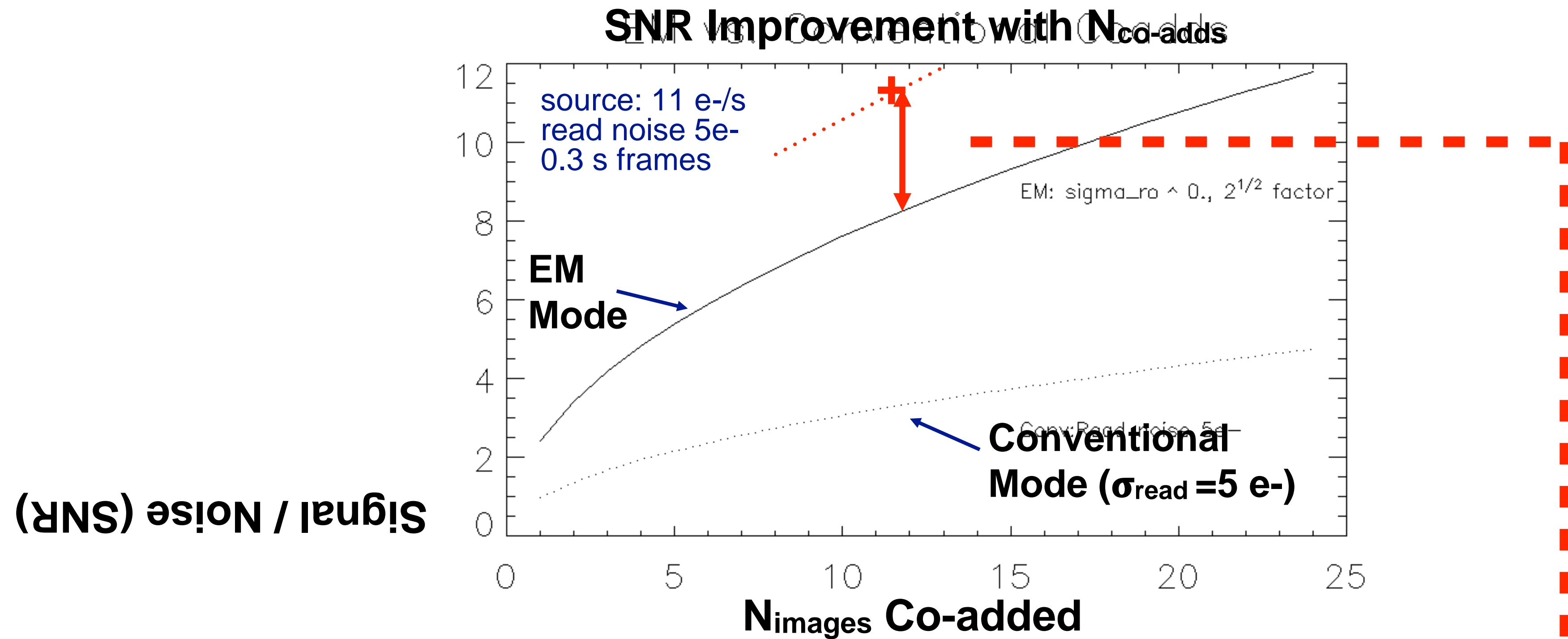


NUTTeIA uses EM mode cameras - high time resolution (when target is bright enough)
Cross-correlation with γ -rays allows us to ID components that do (not) radiate both in optical, γ .

RESULT: FLEXIBILITY → **BOTH sensitivity AND time resolution:**

- Bright sources - don't co-add, use max. time resolution.
- Faint sources - co-add as needed for detections.

But what about **factor $2^{1/2}$** advantage of No EM?



- SINGLE conventional long exposure still better by factor $2^{1/2}$

-BUT NO TIME INFORMATION!

- Is there a way to beat $2^{1/2}$ factor, but still have time resolution?